

$$\begin{aligned} \vec{v} &= \frac{d\vec{x}}{dt} & \omega &= \frac{d\theta}{dt} & \omega_{av} &= \frac{\Delta\theta}{\Delta t} & s &= r\theta & v &= v_0 + at & \omega &= \omega_0 + \alpha t \\ \vec{a} &= \frac{d\vec{v}}{dt} & \alpha &= \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2} & \alpha_{av} &= \frac{\Delta\omega}{\Delta t} & v &= r\omega & x &= x_0 + v_0 t + \frac{1}{2}at^2 & \theta &= \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2 \\ \Delta\theta &= \theta - \theta_0 & \Delta\omega &= \omega - \omega_0 & a_{rad} &= \frac{v^2}{r} = \omega^2 r & v^2 &= v_0^2 + 2a(x - x_0) & \omega^2 &= \omega_0^2 + 2\alpha(\theta - \theta_0) \end{aligned}$$

$$\begin{aligned} \vec{F}_{net} &= m\vec{a} & \vec{\tau}_{net} &= I\vec{\alpha} & I &= \sum_i m_i r_i^2 & I &= \int r^2 dm & I_p &= I_{cm} + Md^2 \\ \vec{\tau} &= \vec{r} \times \vec{F} & \tau &= rF \sin\phi = rF_{\perp} = r_{\perp}F & P &= \tau\omega & a_{cm} &= r\alpha & v_{cm} &= r\omega \end{aligned}$$

$$K = \frac{1}{2}I\omega^2 \quad W_{total} = K_{final} - K_{initial} \quad K_{final} + U_{final} = K_{initial} + U_{initial} + W_{nonconservative} \quad W = \int_{\theta_i}^{\theta_f} \tau d\theta$$

$$\vec{\tau}_{net} = \frac{d\vec{L}}{dt} \quad \vec{L} = \sum \vec{\ell} \quad \vec{\ell} = \vec{r} \times \vec{p} = \vec{r} \times m\vec{v} \quad \ell = rp \sin\phi = rp_{\perp} = r_{\perp}p \quad \vec{L} = I\vec{\omega}$$

$$\begin{aligned} F &= -kx & x(t) &= A \cos(\omega t + \phi) & \omega &= \frac{2\pi}{T} = 2\pi f & T &= 2\pi\sqrt{\frac{m}{k}} & T &= 2\pi\sqrt{\frac{I}{mgd}} \\ U &= \frac{1}{2}kx^2 & a(t) &= -\omega^2 x(t) \end{aligned}$$

$$\frac{F_{\perp}}{A} = Y \left(\frac{\Delta\ell}{\ell_0} \right) \quad \frac{F_{\parallel}}{A} = S \left(\frac{x}{h} \right) \quad B = \frac{-\Delta p}{\Delta V / V_0} \quad v = \sqrt{\frac{B}{\rho}} \quad v = \sqrt{\frac{Y}{\rho}} \quad v = \sqrt{\frac{F}{\mu}}$$

$$y(x,t) = \text{funct}(x \pm vt) \quad y(x,t) = A \cos(kx \pm \omega t + \phi) \quad k = \frac{2\pi}{\lambda} \quad v = \lambda f = \frac{\omega}{k} \quad f_L = \left(\frac{v \pm v_L}{v \pm v_S} \right) f_s$$

$$y(x,t) = 2A \cos\left(\frac{\phi}{2}\right) \sin\left(kx - \omega t - \frac{\phi}{2}\right) \quad y(x,t) = [2A \sin(kx)] \sin(\omega t) \quad P_{av} = \frac{1}{2} \sqrt{\mu F} \omega^2 A^2$$

$$f_n = n f_1; \lambda_n = \frac{2L}{n}; n = 1, 2, 3, \dots \quad p(x,t) = BkA \cos(kx - \omega t) \quad f_{beat} = |f_a - f_b|$$

$$I = \frac{P}{A} = \frac{P}{4\pi r^2} \quad I = \frac{1}{2} \sqrt{\rho B} \omega^2 A^2 \quad \beta = (10 \text{ dB}) \log\left(\frac{I}{I_0}\right) \quad I_0 = 10^{-12} \text{ W/m}^2$$

$$n = \frac{c}{v} \quad n_a \sin\theta_a = n_b \sin\theta_b \quad \frac{1}{f} = \frac{1}{s} + \frac{1}{s'} \quad m = \frac{y'}{y} = -\frac{s'}{s} \quad I = I_{max} \cos^2\phi \quad \tan\theta_p = \frac{n_b}{n_a}$$

$$d \sin\theta = m\lambda \quad m = 0, \pm 1, \pm 2, \dots \text{ (constructive)} \quad I = I_0 \cos^2\left(\frac{\phi}{2}\right) \left(\frac{\sin(\beta/2)}{\beta/2}\right)^2 \quad \phi = \frac{2\pi d}{\lambda} \sin\theta$$

$$a \sin\theta = m\lambda \quad m = \pm 1, \pm 2, \pm 3, \dots \text{ (destructive)} \quad I = I_0 \left(\frac{\sin(\beta/2)}{\beta/2}\right)^2 \quad \beta = \frac{2\pi}{\lambda} a \sin\theta$$